# HYPERIDENTITIES IN SYMMETRIC GRAPH ALGEBRAS

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#### Abstract

Graph algebras establish a connection between directed graphs without multiple edges and special universal algebras of typ (2,0). We say that a graph G satisfies an identity  $s \approx t$  if the corresponding graph algebra  $\underline{A}(G)$  satisfies  $s \approx t$ . A graph G = (V, E) is called a symmetric graph if the graph algebra  $\underline{A}(G)$  satisfies the equation  $xy \approx x(yx)$ . An identity  $s \approx t$  of terms s and t of any type  $\tau$  is called a hyperidentity of an algebra  $\underline{A}$  if whenever the operation symbols occurring in s and tare replaced by any term operations of  $\underline{A}$  of the appropriate arity, the resulting identities hold in  $\underline{A}$ .

In this paper we characterize symmetric graph algebras, identities and hyperidentities in symmetric graph algebras.

# 1 Introduction

An identity  $s \approx t$  of terms s, t of any type  $\tau$  is called a *hyperidentity* of an algebra <u>A</u> if whenever the operation symbols occurring in s and t are replaced by any term operations of <u>A</u> of the appropriate arity, the resulting identity holds in <u>A</u>. Hyperidentities can be defined more precisely using the concept of a hypersubstitution.

We fix a type  $\tau = (n_i)_{i \in I}, n_i > 0$  for all  $i \in I$ , and operation symbols  $(f_i)_{i \in I}$ , where  $f_i$  is  $n_i - ary$ . Let  $W_{\tau}(X)$  be the set of all terms of type  $\tau$  over some fixed alphabet X, and let  $Alg(\tau)$  be the class of all algebras of type  $\tau$ .

Key words: Gidentity, hyperidentity, term, normal form term, binary algebra, graph algebra, symmetric graph algebra.

 $<sup>2000~\</sup>mathrm{AMS}$  Mathematics Subject Classification:  $08\mathrm{C}15,\,08\mathrm{A}15,\,08\mathrm{B}15$ 

Then a mapping

$$\sigma: \{f_i | i \in I\} \longrightarrow W_\tau(X)$$

which assigns to every  $n_i - ary$  operation symbol  $f_i$  an  $n_i - ary$  term will be called a *hypersubstitution of type*  $\tau$  (for short, a hypersubstitution). By  $\hat{\sigma}$  we denote the extension of the hypersubstitution  $\sigma$  to a mapping

$$\hat{\sigma}: W_{\tau}(X) \longrightarrow W_{\tau}(X).$$

The term  $\hat{\sigma}[t]$  is defined inductively by

(i)  $\hat{\sigma}[x] = x$  for any variable x in the alphabet Xand

(ii)  $\hat{\sigma}[f_i(t_1, ..., t_{n_i})] = \sigma(f_i)^{W_{\tau}(X)}(\hat{\sigma}[t_1], ..., \hat{\sigma}[t_{n_i}]).$ Here  $\sigma(f_i)^{W_{\tau}(X)}$  on the right hand side of (ii) is the operation induced by  $\sigma(f_i)$  on the term algebra  $W_{\tau}(X)$ .

Graph algebras have been invented in [11] to obtain examples of nonfinitely based finite algebras. To recall this concept, let G = (V, E) be a (directed) graph with the vertex set V and the set of edges  $E \subseteq V \times V$ . Define the graph algebra  $\underline{A}(G)$  corresponding to G to have the underlying set  $V \cup \{\infty\}$ , where  $\infty$ is a symbol outside V, and two basic operations, a nullary operation pointing to  $\infty$  and a binary one denoted by juxtaposition, given for  $u, v \in V \cup \{\infty\}$  by

$$uv = \begin{cases} u, & \text{if } (u, v) \in E, \\ \infty, & \text{otherwise.} \end{cases}$$

Graph identities were characterized in [3] by using the rooted graph of a term t where the vertices correspond to the variables occurring in t. Since on a graph algebra we have one nullary and one binary operation,  $\sigma(f)$  in this case is a *binary term* in  $W_{\tau}(X)$ , i.e. a term built up from variables of a twoelement alphabet and a binary operation symbol f corresponding to the binary operation of the graph algebra.

In [9] R. Pöschel has shown that any term over the class of all graph algebras can be uniquely represented by a normal form term and that there is an algorithm to construct the normal form term to every given term t.

In [1] K. Denecke and T. Poomsa-ard characterized graph hyperidentities by using normal form graph hypersubstitutions.

In [6] T. Poomsa-ard characterized associative graph hyperidentities by using normal form graph hypersubstitutions.

In [7] T. Poomsa-ard, J. Wetweerapong and C. Samartkoon characterized idempotent graph hyperidentities by using normal form graph hypersubstitutions.

In [8] T. Poomsa-ard, J. Wetweerapong and C. Samartkoon characterized transitive graph hyperidentities by using normal form graph hypersubstitutions.

A graph G = (V, E) is called *symmetric* if the graph  $\underline{A}(G)$  satisfied the equation  $xy \approx x(yx)$ . In this paper we characterize symmetric graph algebras, identities and hyperidentities in symmetric graph algebras.

## 2 Symmetric graph algebras.

We begin with a more precise definition of terms of the type of graph algebras.

**Definition 2.1.** The set  $W_{\tau}(X)$  of all terms over the alphabet

$$X = \{x_1, x_2, x_3, \dots\}$$

is defined inductively as follows:

(i) every variable  $x_i$ , i = 1, 2, 3, ..., and  $\infty$  are terms;

(ii) if  $t_1$  and  $t_2$  are terms, then  $f(t_1, t_2)$  is a term; instead of  $f(t_1, t_2)$  we will write  $t_1t_2$ , for short;

(iii)  $W_{\tau}(X)$  is the set of all terms which can be obtained from (i) and (ii) in finitely many steps.

Terms built up from the two-element set  $X_2 = \{x_1, x_2\}$  of variables are thus binary terms. We denote the set of all binary terms by  $W_{\tau}(X_2)$ . The leftmost variable of a term t is denoted by L(t) and rightmost variable of a term t is denoted by R(t). A term, in which the symbol  $\infty$  occurs is called a *trivial term*.

**Definition 2.2.** To each non-trivial term t of type  $\tau = (2,0)$  one can define a directed graph G(t) = (V(t), E(t)), where the vertex set V(t) is the set var(t) of all variables occurring in t, and where E(t) is defined inductively by

 $E(t) = \phi$  if t is a variable and  $E(t_1t_2) = E(t_1) \cup E(t_2) \cup \{(L(t_1), L(t_2))\},\$ 

when  $t = t_1 t_2$  is a compound term and  $L(t_1), L(t_2)$  are the leftmost variables in  $t_1$  and  $t_2$  respectively.

L(t) is a root of the graph G(t) and the pair (G(t), L(t)) is the rooted graph corresponding to t. Formally, to every trivial term t we assign the empty graph  $\phi$ .

**Definition 2.3.** We say that a graph G = (V, E) satisfies an identity  $s \approx t$  if the corresponding graph algebra A(G) satisfies  $s \approx t$  (i.e. we have s = t for every assignment  $V(s) \cup V(t) \to V \cup \overline{\{\infty\}}$ ), and in this case, we write  $G \models s \approx t$ .

**Definition 2.4.** Let G = (V, E) and G' = (V', E') be graphs. A homomorphism h from G into G' is a mapping  $h : V \to V'$  carrying edges to edges, that is, for which  $(u, v) \in E$  implies  $(h(u), h(v)) \in E'$ .

In [3] it was proved:

**Proposition 2.1.** Let s and t be non-trivial terms from  $W_{\tau}(X)$  with variables  $V(s) = V(t) = \{x_0, x_1, ..., x_n\}$  and L(s) = L(t). Then a graph G = (V, E) satisfies  $s \approx t$  if and only if the graph algebra A(G) has the following property:

A mapping  $h: V(s) \longrightarrow V$  is a homomorphism from G(s) into G iff it is a homomorphism from G(t) into G.

Proposition 2.1 gives a method to check whether a graph G = (V, E) satisfies the equation  $s \approx t$ . Hence, we can check whether a graph G = (V, E) has a symmetric graph algebra by the following proposition.

**Proposition 2.2.** Let G = (V, E) be a graph. Then G has a symmetric graph algebra if and only  $(a, b) \in E \Leftrightarrow (b, a) \in E$ .

**Proof** Suppose that G = (V, E) has a symmetric graph algebra. Let s and t be non-trivial terms such that s = xy, t = x(yx). Let  $(a, b) \in E$  and  $h : V(s) \to V$  be the restriction function of the variables such that h(x) = a, h(y) = b. We see that h is a homomorphism from G(s) into G. Since G has a symmetric graph algebra. By Proposition 2.1, we have that h is a homomorphism from G(t) into G. Since  $(y, x) \in E(t)$ , we get  $(h(y), h(x)) = (b, a) \in E$ . Suppose that  $(b, a) \in E$ . If we map h(x) = b, h(y) = a, then h is a homomorphism from G(s) into G. By the same manner, we have h is a homomorphism from G(t) into G. Since  $(y, x) \in E(t)$ , hence  $(h(y), h(x)) = (a, b) \in E$ .

Conversely, suppose that G = (V, E) is a graph such that  $(a, b) \in E$  if and only if  $(b, a) \in E$ . Let s and t be non-trivial terms such that s = xy, t = x(yx). Suppose that  $h : V(s) \to V$  is a homomorphism from G(s) into G. Since  $(x, y) \in E(s)$ , we have  $(h(x), h(y)) \in E$ . By assumption, we get  $(h(y), h(x)) \in$ E. Therefore h is a homomorphism from G(t) into G. Suppose that h is a homomorphism from G(t) into G. Then, it is clear that h is a homomorphism from G(s) into G. By Proposition 2.1, we get that A(G) satisfies  $s \approx t$ .

From Proposition 2.2 we see that graphs which have symmetric graph algebras are the following graphs:



and all graphs such that every induced subgraph with at most two vertices of each component is one of these graphs.

## 3 Identities in symmetric graph algebras.

Graph identities were characterized in [3] by the following proposition:

**Proposition 3.1.** A non-trivial equation  $s \approx t$  is an identity in the class of all graph algebras iff either both terms s and t are trivial or none of them is trivial, G(s) = G(t) and L(s) = L(t).

Further it was proved.

**Proposition 3.2.** Let G = (V, E) be a graph and let  $h : X \cup \{\infty\} \longrightarrow V \cup \{\infty\}$ be an evaluation of the variables such that  $h(\infty) = \infty$ . Consider the canonical extension of h to the set of all terms. Then there holds: if t is a trivial term then  $h(t) = \infty$ . Otherwise, if  $h : G(t) \longrightarrow G$  is a homomorphism of graphs, then h(t) = h(L(t)), and if h is not a homomorphism of graphs, then  $h(t) = \infty$ .

In [6] the following lemma was proved:

**Lemma 3.1.** Let G = (V, E) be a graph, let t be a term and let

$$h: X \longrightarrow V \cup \{\infty\}$$

be an evaluation of the variables. Then:

(i) If  $h : G(t) \longrightarrow G$  with the property that the subgraph of G induced by h(V(t)) is complete, then h(t) = h(L(t));

(ii) If  $h: G(t) \longrightarrow G$  with the property that the subgraph of G induced by h(V(t)) is disconnected, then  $h(t) = \infty$ .

Now, we apply our results to characterize all identities in the class of all symmetric graph algebras. Clearly, if s and t are trivial, then  $s \approx t$  is an identity in the class of all symmetric graph algebras and  $x \approx x, x \in X$  is an identity in the class of all symmetric graph algebras too. So we consider the case that s and t are non-trivial and different from variables. Then all identities in the class of all symmetric graph algebras are characterized by the following theorem:

**Theorem 3.1.** Let s and t be non-trivial terms. Then  $s \approx t$  is an identity in the class of all symmetric graph algebras if and only if the following conditions are satisfied:

(i) L(s) = L(t),

(ii) V(s) = V(t),

(iii) for any  $x, y \in V(s)$ ,  $(x, y) \in E(s)$  or  $(y, x) \in E(s)$  if and only if  $(x, y) \in E(t)$  or  $(y, x) \in E(t)$ .

**Proof** Suppose that  $s \approx t$  is an identity in the class of all symmetric graph algebras. Since any complete graph is symmetric, it follows that L(s) = L(t) and V(s) = V(t).

Suppose that  $(x, y) \in E(s)$  or  $(y, x) \in E(s)$  but  $(x, y) \notin E(t)$  and  $(y, x) \notin E(t)$ . If x = y, then consider the graph G = (V, E) such that  $V = \{0, 1\}, E = \{(0, 1), (1, 0), (1, 1)\}$ . By Proposition 2.2,  $\underline{A}(G)$  has a symmetric graph algebra. Let  $h: V(s) \to V$  be the restriction of an evaluation of the variables such that h(x) = 0, h(z) = 1 for all  $z \neq x$ . We see that  $h(s) = \infty$  and h(t) = h(L(t)). Hence, A(G) does not satisfy  $s \approx t$ .

Suppose that  $x \neq y$ . Consider the symmetric graph G = (V, E) such that  $V = \{0, 1, 2\}, E = \{(0, 0), (0, 1), (1, 0), (1, 1), (1, 2), (2, 1), (2, 2)\}$ . Let  $h : V(s) \to V$  be the restriction of an evaluation of the variables such that h(x) = 0, h(y) = 2 and h(z) = 1 for all  $z \neq x, z \neq y$ . We get that  $h(s) = \infty$  and h(t) = h(L(t)). Hence, A(G) does not satisfy  $s \approx t$ .

Conversely, suppose that s and t are non-trivial terms satisfying (i), (ii) and (iii). Let G = (V, E) be a symmetric graph and let  $h : V(s) \to V$  be the restriction function of the variables. Suppose that h is a homomorphism from G(s) into G and let  $(x, y) \in E(t)$ . By (iii) we get  $(x, y) \in E(s)$  or  $(y, x) \in E(s)$ . If  $(x, y) \in E(s)$ , then we have  $(h(x), h(y)) \in E$ . If  $(y, x) \in E(s)$ , then  $(h(y), h(x)) \in E$ . Since G is a symmetric graph, we get  $(h(x), h(y)) \in E$ . Hence h is a homomorphism from G(t) into G. By the same way, if h is a homomorphism from G(t) into G, then we can prove that it is a homomorphism from G(s) into G. By Proposition 2.1, we get that A(G) satisfies  $s \approx t$ .

## 4 Hyperidentities in symmetric graph algebras

Let SG be the classes of all symmetric graph algebras and let IdSG be the set of all identities satisfied in SG. Now we want to make precise the concept of a hypersubstitution for graph algebras.

**Definition 4.1.** A mapping  $\sigma : \{f, \infty\} \to W_{\tau}(X_2)$ , where f is the operation symbol corresponding to the binary operation of a graph algebra is called graph hypersubstitution if  $\sigma(\infty) = \infty$  and  $\sigma(f) = s \in W_{\tau}(X_2)$ . The graph hypersubstitution with  $\sigma(f) = s$  is denoted by  $\sigma_s$ .

**Definition 4.2.** An identity  $s \approx t$  is a symmetric graph hyperidentity iff for all graph hypersubstitutions  $\sigma$ , the equations  $\hat{\sigma}[s] \approx \hat{\sigma}[t]$  are identities in SG.

If we want to check that  $s \approx t$  is a hyperidentity in SG, we can restrict ourselves to a (small) subset of HypG - the set of all graph hypersubstitutions.

In [4] the following relation between hypersubstitutions was defined:

**Definition 4.3.** Two graph hypersubstitutions  $\sigma_1, \sigma_2$  are called *SG-equivalent* iff  $\sigma_1(f) \approx \sigma_2(f)$  is an identity in *SG*. In this case we write  $\sigma_1 \sim_{SG} \sigma_2$ .

In [2] (see also [4]) the following lemma was proved:

**Lemma 4.1.** If  $\hat{\sigma}_1[s] \approx \hat{\sigma}_1[t] \in IdSG$  and  $\sigma_1 \sim_{SG} \sigma_2$  then  $\hat{\sigma}_2[s] \approx \hat{\sigma}_2[t] \in IdSG$ .

Therefore it is enough to consider the quotient set  $Hyp\mathcal{G}/\sim_{S\mathcal{G}}$ .

In [7] it was shown that any non-trivial term t over the class of graph algebras has a uniquely determined normal form term NF(t) and there is an algorithm to construct the normal form term to a given term t. Now we want to describe how to construct the normal form term . Let t be a non-trivial term. The normal form term of t is the term NF(t) constructed by the following algorithm:

(i) Construct G(t) = (V(t), E(t))

(ii) Construct for every  $x \in V(t)$  the list  $l_x = (x_{i_1}, ..., x_{i_{k(x)}})$  of all outneighbors (i.e.  $(x, x_{i_j}) \in E(t), 1 \leq j \leq k(x)$ ) ordered by increasing indices  $i_1 \leq ... \leq i_{k(x)}$  and let  $s_x$  be the term  $(...((x_{i_1})x_{i_2})...x_{i_{k(x)}})$ .

(iii) Starting with x := L(t), Z := V(t), s := L(t), choose the variable  $x_i \in Z \cap V(s)$  with the least index i, substitute the first occurrence of  $x_i$  by the term  $s_{x_i}$ , denote the resulting term again by s and put  $Z := Z \setminus \{x_i\}$ . While  $Z \neq \phi$  continue this procedure. The resulting term is the normal form NF(t). The algorithm stops after a finite number of steps, since G(t) is a rooted graph . Without difficulties one shows G(NF(t)) = G(t), L(NF(t)) = L(t).

In [1] the following definition was given:

**Definition 4.4.** The graph hypersubstitution  $\sigma_{NF(t)}$ , is called *normal form* graph hypersubstitution. Here NF(t) is the normal form of the binary term t.

Since for any binary term t the rooted graphs of t and NF(t) are the same, we have  $t \approx NF(t) \in IdSG$ . Then for any graph hypersubstitution  $\sigma_t$  with  $\sigma_t(f) = t \in W_\tau(X_2)$ , one obtains  $\sigma_t \sim_{SG} \sigma_{NF(t)}$ .

In [1] all rooted graphs with at most two vertices were considered. Then we formed the corresponding binary terms and used the algorithm to construct normal form terms. The result is given in the following table.

normal form term	graph hypers.	normal form term	graph hypers.		
$x_1 x_2$	$\sigma_0$	$x_1$	$\sigma_1$		
$x_2$	$\sigma_2$	$x_1x_1$	$\sigma_3$		
$x_2 x_2$	$\sigma_4$	$x_2x_1$	$\sigma_5$		
$(x_1x_1)x_2$	$\sigma_{6}$	$(x_2x_1)x_2$	$\sigma_7$		
$x_1(x_2x_2)$	$\sigma_8$	$x_2(x_1x_1)$	$\sigma_9$		
$(x_1x_1)(x_2x_2)$	$\sigma_{10}$	$(x_2(x_1x_1))x_2$	$\sigma_{11}$		
$x_1(x_2x_1)$	$\sigma_{12}$	$x_2(x_1x_2)$	$\sigma_{13}$		
$(x_1x_1)(x_2x_1)$	$\sigma_{14}$	$x_2((x_1x_1)x_2)$	$\sigma_{15}$		
$x_1((x_2x_1)x_2)$	$\sigma_{16}$	$(x_2(x_1x_2))x_2$	$\sigma_{17}$		
$(x_1x_1)((x_2x_1)x_2)$	$\sigma_{18}$	$(x_2((x_1x_1)x_2))x_2$	$\sigma_{19}$		

By Theorem 3.1, we have the following relations:

- (1)  $\sigma_0 \sim_{\mathcal{SG}} \sigma_{12}$ ,
- (2)  $\sigma_5 \sim_{\mathcal{SG}} \sigma_{13}$ ,
- (3)  $\sigma_6 \sim_{SG} \sigma_{14}$ ,
- (4)  $\sigma_7 \sim_{SG} \sigma_{17}$ ,
- (5)  $\sigma_8 \sim_{SG} \sigma_{16}$ ,
- (6)  $\sigma_9 \sim_{SG} \sigma_{15}$ ,
- (7)  $\sigma_{10} \sim_{\mathcal{SG}} \sigma_{18}$ ,
- (8)  $\sigma_{11} \sim_{SG} \sigma_{19}$ .

Let  $M_{SG}$  be the set of all normal form graph hypersubstitutions in SG. Then we get,

$$M_{SG} = \{\sigma_0, \sigma_1, \sigma_2, \sigma_3, \sigma_4, \sigma_5, \sigma_6, \sigma_7, \sigma_8, \sigma_9, \sigma_{10}, \sigma_{11}\}$$

We defined the product of two normal form graph hypersubstitutions in  $M_{\mathcal{SG}}$  as follows.

**Definition 4.5.** The product  $\sigma_{1N} \circ_N \sigma_{2N}$  of two normal form graph hypersubstitutions is defined by  $(\sigma_{1N} \circ_N \sigma_{2N})(f) = NF(\hat{\sigma}_{1N}[\sigma_{2N}(f)]).$ 

The following table gives the multiplication of elements in  $M_{SG}$ .

$\circ_N$	$\sigma_0$	$\sigma_1$	$\sigma_2$	$\sigma_3$	$\sigma_4$	$\sigma_5$	$\sigma_6$	$\sigma_7$	$\sigma_8$	$\sigma_9$	$\sigma_{10}$	$\sigma_{11}$
$\sigma_0$	$\sigma_0$	$\sigma_1$	$\sigma_2$	$\sigma_3$	$\sigma_4$	$\sigma_5$	$\sigma_6$	$\sigma_7$	$\sigma_8$	$\sigma_9$	$\sigma_{10}$	$\sigma_{11}$
$\sigma_1$	$\sigma_1$	$\sigma_1$	$\sigma_2$	$\sigma_1$	$\sigma_2$	$\sigma_2$	$\sigma_1$	$\sigma_2$	$\sigma_1$	$\sigma_1$	$\sigma_1$	$\sigma_2$
$\sigma_2$	$\sigma_2$	$\sigma_1$	$\sigma_2$	$\sigma_1$	$\sigma_2$	$\sigma_1$	$\sigma_2$	$\sigma_2$	$\sigma_2$	$\sigma_1$	$\sigma_2$	$\sigma_2$
$\sigma_3$	$\sigma_3$	$\sigma_1$	$\sigma_2$	$\sigma_3$	$\sigma_4$	$\sigma_4$	$\sigma_3$	$\sigma_4$	$\sigma_3$	$\sigma_4$	$\sigma_3$	$\sigma_4$
$\sigma_4$	$\sigma_4$	$\sigma_1$	$\sigma_2$	$\sigma_3$	$\sigma_4$	$\sigma_3$	$\sigma_4$	$\sigma_4$	$\sigma_4$	$\sigma_3$	$\sigma_4$	$\sigma_4$
$\sigma_5$	$\sigma_5$	$\sigma_1$	$\sigma_2$	$\sigma_3$	$\sigma_4$	$\sigma_0$	$\sigma_9$	$\sigma_5$	$\sigma_7$	$\sigma_6$	$\sigma_{11}$	$\sigma_9$
$\sigma_6$	$\sigma_6$	$\sigma_1$	$\sigma_2$	$\sigma_3$	$\sigma_4$	$\sigma_7$	$\sigma_6$	$\sigma_7$	$\sigma_{10}$	$\sigma_{11}$	$\sigma_{10}$	$\sigma_{11}$
$\sigma_7$	$\sigma_7$	$\sigma_1$	$\sigma_2$	$\sigma_3$	$\sigma_4$	$\sigma_6$	$\sigma_{11}$	$\sigma_{11}$	$\sigma_7$	$\sigma_6$	$\sigma_{11}$	$\sigma_{11}$
$\sigma_8$	$\sigma_8$	$\sigma_1$	$\sigma_2$	$\sigma_3$	$\sigma_4$	$\sigma_9$	$\sigma_{10}$	$\sigma_{11}$	$\sigma_8$	$\sigma_9$	$\sigma_{10}$	$\sigma_{11}$
$\sigma_9$	$\sigma_9$	$\sigma_1$	$\sigma_2$	$\sigma_3$	$\sigma_4$	$\sigma_8$	$\sigma_9$	$\sigma_{11}$	$\sigma_{11}$	$\sigma_{10}$	$\sigma_{11}$	$\sigma_{11}$
$\sigma_{10}$	$\sigma_{10}$	$\sigma_1$	$\sigma_2$	$\sigma_3$	$\sigma_4$	$\sigma_{11}$	$\sigma_{10}$	$\sigma_{11}$	$\sigma_{10}$	$\sigma_{11}$	$\sigma_{10}$	$\sigma_{11}$
$\sigma_{11}$	$\sigma_{11}$	$\sigma_1$	$\sigma_2$	$\sigma_3$	$\sigma_4$	$\sigma_{10}$	$\sigma_{11}$	$\sigma_{11}$	$\sigma_{11}$	$\sigma_{10}$	$\sigma_{11}$	$\sigma_{11}$

In [1] the concept of a leftmost normal form graph hypersubstitution was defined.

**Definition 4.6.** A graph hypersubstitution  $\sigma$  is called *leftmost* if  $L(\sigma(f)) = x_1$ .

The set  $M_{L(SG)}$  of all leftmost normal form graph hypersubstitutions in  $M_{SG}$  contains exactly the following elements.

$$M_{L(\mathcal{SG})} = \{\sigma_0, \sigma_1, \sigma_3, \sigma_6, \sigma_8, \sigma_{10}\}.$$

In [5] the concept of a proper hypersubstitution of a class of algebras was introduced.

**Definition 4.7.** A hypersubstitution  $\sigma$  is called *proper with respect to a class*  $\mathcal{K}$  of algebras if  $\hat{\sigma}[s] \approx \hat{\sigma}[t] \in Id\mathcal{K}$  for all  $s \approx t \in Id\mathcal{K}$ .

A graph hypersubstitution with the property that  $\sigma(f)$  contains both variables  $x_1$  and  $x_2$  is called *regular*. It is easy to check that the set of all regular graph hypersubstitutions forms a groupoid  $M_{reg}$ .

We want to prove that  $\{\sigma_0, \sigma_{10}\}$  is the set of all proper normal form graph hypersubstitutions with respect to SG.

In [1] the following lemma was proved.

**Lemma 4.2.** For each non-trivial term  $s, (s \neq x \in X)$  and for all  $u, v \in X$ , we have:

 $\begin{aligned} (i)E(\hat{\sigma_6}[s]) &= E(s) \cup \{(u,u) | (u,v) \in E(s)\},\\ (ii)E(\hat{\sigma_8}[s]) &= E(s) \cup \{(v,v) | (u,v) \in E(s)\},\\ and \end{aligned}$ 

 $(iii)E(\hat{\sigma}_{12}[s]) = E(s) \cup \{(v,u) | (u,v) \in E(s)\}.$ 

In [1] the concept of a *dual term*  $s^d$  of the non-trivial term s was defined in the following way:

If  $s = x \in X$ , then  $x^d = x$ ; if  $s = t_1 t_2$ , then  $s^d = t_2^d t_1^d$ . The dual term  $s^d$  can be obtained by application of the graph hypersubstitution  $\sigma_5$ , namely,  $\hat{\sigma}_5[s] = s^d$ . Then, we can prove the following lemma:

**Lemma 4.3.** For each non-trivial term  $s, (s \neq x \in X)$  and for all  $u, v \in X$ , we have:

 $\begin{aligned} (i)E(\hat{\sigma}_{7}[s]) &= E(s^{d}) \cup \{(u,u) | (u,v) \in E(s^{d})\},\\ (ii)E(\hat{\sigma}_{9}[s]) &= E(s^{d}) \cup \{(v,v) | (u,v) \in E(s^{d})\},\\ and \end{aligned}$ 

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 $(iii)E(\hat{\sigma_{10}}[s]) = E(s) \cup \{(u, u), (v, v) | (u, v) \in E(s)\}.$ 

**Proof** We prove the equation by induction with respect to the complexity of terms. Assume that s = uv, where u, v are variables. Then

$$E(\hat{\sigma_7}[s]) = E((vu)v) = \{(v, u), (v, v)\} = E(s^d) \cup \{(v, v)\},$$
$$E(\hat{\sigma_9}[s]) = E(v(uu)) = \{(u, u), (v, u)\} = E(s^d) \cup \{(u, u)\},$$
$$E(\hat{\sigma_{10}}[s]) = E((uu)(vv)) = \{(u, v), (u, u), (v, v)\} = E(s) \cup \{(u, u), (v, v)\}.$$

Assume that  $s = s_1 s_2$  and that at least one of the terms  $s_1, s_2$  is not a variable, assume further that  $s_1, s_2$  fulfil the equation which we want to prove. Then we have

$$\begin{split} &E(\hat{\sigma_7}[s_1]) = E(\hat{\sigma_7}[s_1s_2]) = E((\hat{\sigma_7}[s_2]\hat{\sigma_7}[s_1])\hat{\sigma_7}[s_2]) \\ &= E(\hat{\sigma_7}[s_1]) \cup E(\hat{\sigma_7}[s_2]) \cup \{(L(\hat{\sigma_7}[s_2]), L(\hat{\sigma_7}[s_2]), L(\hat{\sigma_7}[s_2]), L(\hat{\sigma_7}[s_2])), \\ &= E(s_1^d]) \cup \{(u, u) | (u, v) \in E(s_1^d)\} \cup E(s_2^d) \cup \{(u', u') | (u', v') \in E(s_2^d)\} \\ &\cup \{(L(s_2^d), L(s_1^d])), (L(s_2^d]), L(s_2^d]))\} \\ &= E(s^d) \cup \{(u, u) | (u, v) \in E(s^d)\}. \\ &E(\hat{\sigma_9}[s_1]) = E(\hat{\sigma_9}[s_1s_2]) = E(\hat{\sigma_9}[s_2](\hat{\sigma_9}[s_1]\hat{\sigma_9}[s_1])) \\ &= E(\hat{\sigma_9}[s_1]) \cup E(\hat{\sigma_2}[s_2]) \cup \{(L(\hat{\sigma_9}[s_2]), L(\hat{\sigma_9}[s_1])), (L(\hat{\sigma_9}[s_1]), L(\hat{\sigma_9}[s_1])), \\ &= E(s_1^d]) \cup \{(v, v) | (u, v) \in E(s_1^d)\} \cup E(s_2^d) \cup \{(v', v') | (u', v') \in E(s_2^d)\} \\ &\cup \{(L(s_2^d), L(s_1^d)), (L(s_1^d]), L(s_1^d)) \\ &= E(s^d) \cup \{(v, v) | (u, v) \in E(s^d)\}. \\ &E(\hat{\sigma_{10}}[s_1]) \cup E(\hat{\sigma_{10}}[s_1s_2]) = E((\hat{\sigma_{10}}[s_1])\hat{\sigma_{10}}[s_1])(\hat{\sigma_{10}}[s_2]\hat{\sigma_{10}}[s_2])) \\ &= E(s_1^1) \cup \{(u, u), (v, v) | (u, v) \in E(s_1)\} \cup E(s_2) \cup \{(u', u'), (v', v') | (u', v') \in E(s_2)\}, L(\hat{\sigma_{10}}[s_2]))\} \\ &= E(s_1) \cup \{(u, u), (v, v) | (u, v) \in E(s_1)\} \cup E(s_2) \cup \{(u', u'), (v', v') | (u', v') \in E(s_2)\} \cup \{(L(s_1), L(s_1)), (L(s_1), L(s_2)), (L(s_2)), L(s_2))\} \\ &= E(s) \cup \{(u, u), (v, v) | (u, v) \in E(s)\}. \\ \\ \end{array}$$

Then we obtain:

**Theorem 4.1.**  $\{\sigma_0, \sigma_{10}\}$  is the set of all proper graph hypersubstitution with respect to the class SG of symmetric graph algebras.

**Proof** If  $s \approx t \in IdSG$  and s, t are trivial terms, then for every graph hypersubstitution  $\sigma \in \{\sigma_0, \sigma_{10}\}$  the term  $\hat{\sigma}[s]$  and  $\hat{\sigma}[t]$  are also trivial and thus  $\hat{\sigma}[s] \approx \hat{\sigma}[t] \in IdSG$ . By the same manner, we see that  $\hat{\sigma}[s] \approx \hat{\sigma}[t] \in IdSG$  for every  $\sigma \in \{\sigma_0, \sigma_{10}\}$ , if s = t = x.

Now, assume that s and t are non-trivial terms, different from variables, and  $s \approx t \in IdSG$ . Then (i) - (iii) of the Theorem 3.1 hold.

For  $\sigma_{10}$  we obtain

$$L(\hat{\sigma}_{10}[s]) = L(s) = L(t) = L(\hat{\sigma}_{10}[t]).$$

Since  $\sigma_{10}$  is regular, we have  $V(\hat{\sigma}_{10}[s]) = V(s) = V(t) = V(\hat{\sigma}_{10}[t])$ . By Lemma 4.2, we have

$$E(\hat{\sigma}_{10}[s]) = E(s) \cup \{(u, u), (v, v) \mid (u, v) \in E(s)\},\$$
$$E(\hat{\sigma}_{10}[t]) = E(t) \cup \{(u, u), (v, v) \mid (u, v) \in E(t)\}.$$

For any  $x, y \in V(s)$ , suppose that  $(x, y) \in E(\hat{\sigma}_{10}[s])$ . Suppose that x = y(i.e.  $(x, y) = (x, x) \in E(\hat{\sigma}_{10}[s])$ ). If  $(x, x) \in E(s)$ , then by (iii)  $(x, x) \in E(t)$ . Hence  $(x, x) \in E(\hat{\sigma}_{10}[t])$ . If  $(x, x) \notin E(s)$ , then there exists  $z \neq x$  such that  $(x, z) \in E(s)$  or  $(z, x) \in E(s)$ . By (iii), we get  $(x, z) \in E(t)$  or  $(z, x) \in E(t)$ . Hence  $(x, x) \in E(\hat{\sigma}_{10}[t])$ . If  $x \neq y$ , then  $(x, y) \in E(s)$ . By (iii), we get  $(x, y) \in E(t)$  or  $(y, x) \in E(t)$ . Therefore  $(x, y) \in E(\hat{\sigma}_{10}[t])$  or  $(y, x) \in E(\hat{\sigma}_{10}[t])$ . Hence  $\hat{\sigma}_{10}[s] \approx \hat{\sigma}_{10}[t] \in Id\mathcal{SG}$ .

For any  $\sigma \notin \{\sigma_0, \sigma_{10}\}$ , we give an identity  $s \approx t \in IdS\mathcal{G}$  such that  $\hat{\sigma}[s] \approx \hat{\sigma}[t] \notin IdS\mathcal{G}$ . Clearly, if s and t are trivial terms with different leftmost and different rightmost, then  $\hat{\sigma}_1[s] \approx \hat{\sigma}_1[t] \notin IdS\mathcal{G}$ ,  $\hat{\sigma}_2[s] \approx \hat{\sigma}_2[t] \notin IdS\mathcal{G}$ ,  $\hat{\sigma}_3[s] \approx \hat{\sigma}_3[t] \notin IdS\mathcal{G}$  and  $\hat{\sigma}_4[s] \approx \hat{\sigma}_4[t] \notin IdS\mathcal{G}$ .

Let  $s = x_1 x_2$  and  $t = x_1(x_2 x_1)$ . By Theorem 3.1, we get  $s \approx t \in IdSG$ . Since

$$\begin{aligned} \hat{\sigma}_6[s] &= \hat{\sigma}_6[x_1x_2] = (x_1x_1)x_2, \\ \hat{\sigma}_6[t] &= \hat{\sigma}_6[x_1(x_2x_1)] = (x_1x_1)((x_2x_2)x_1), \\ \hat{\sigma}_8[s] &= \hat{\sigma}_8[x_1x_2] = x_1(x_2x_2) \end{aligned}$$

and

$$\hat{\sigma}_8[t] = \hat{\sigma}_8[x_1(x_2x_1)] = x_1((x_2(x_1x_1))(x_2(x_1x_1))).$$

We see that  $(x_2, x_2) \in \hat{\sigma}_6[t]$  but  $(x_2, x_2) \notin \hat{\sigma}_6[s]$  and  $(x_1, x_1) \in \hat{\sigma}_8[t]$  but  $(x_1, x_1) \notin \hat{\sigma}_8[s]$ . Hence  $\hat{\sigma}_6[s] \approx \hat{\sigma}_6[t] \notin IdS\mathcal{G}$  and  $\hat{\sigma}_8[s] \approx \hat{\sigma}_8[t] \notin IdS\mathcal{G}$ .

Now, let  $s = (x_1x_2)x_1$  and  $t = ((x_1x_2)x_1)x_2$ . By Theorem 3.1, we have  $s \approx t \in IdSG$ . If  $\sigma \in \{\sigma_5, \sigma_7, \sigma_9, \sigma_{11}\}$ , then  $L(\sigma(f) = x_2$ . We see that  $L(\hat{\sigma}[s]) = x_1$  and  $L(\hat{\sigma}[t]) = x_2$  for all  $\sigma \in \{\sigma_5, \sigma_7, \sigma_9, \sigma_{11}\}$ . Thus  $\hat{\sigma}[s] \approx \hat{\sigma}[t] \notin IdSG$ .  $\Box$ 

Now we apply our results to characterize all hyperidentities in the class of all transitive graph algebras. Clearly, if s and t are trivial terms, then  $s \approx t$  is a hyperidentity in SG if and only if they have the same leftmost and the same rightmost and  $x \approx x, x \in X$  is a hyperidentity in SG too. So we consider the case that s and t are non-trivial and different from variables.

**Theorem 4.2.** An identity  $s \approx t$  in SG, where s, t are non-trivial and  $s \neq x, t \neq x$ , is a hyperidentity in SG if and only if the following conditions are satisfied:

(i)  $s^d \approx t^d \in Id\mathcal{SG}$ ,

(ii) for all  $x \in V(s), \exists y \in V(s), (x, y) \in E(s) \Leftrightarrow \exists z \in V(t), (x, z) \in E(t),$ 

(iii) for all  $x \in V(s), \exists y \in V(s), (y, x) \in E(s) \Leftrightarrow \exists z \in V(t), (z, x) \in E(t),$ (iv) for all  $x' \in V(s), \exists y' \in V(s), (x', y') \in E(s^d) \Leftrightarrow \exists z' \in V(t), (x', z') \in E(t^d).$ 

(v) for all  $x' \in V(s), \exists y' \in V(s), (y', x') \in E(s^d) \Leftrightarrow \exists z' \in V(t), (z', x') \in E(t^d).$ 

**Proof** If  $s \approx t$  is a hyperidentity in SG, then  $\hat{\sigma}_5[s] \approx \hat{\sigma}_5[t]$  is an identity in SG, i.e.,  $s^d \approx s^d \in IdSG$ .

Suppose that there exists  $x \in V(s)$  such that  $\exists y \in V(s), (x, y) \in E(s)$  but  $\exists z \in V(t), (x, z) \in E(t)$ . We see that  $(x, x) \in E(\hat{\sigma}_6[s])$  but  $(x, x) \notin E(\hat{\sigma}_6[t])$ . Hence  $\hat{\sigma}_6[s] \approx \hat{\sigma}_6[t] \notin IdSG$ .

Suppose that there exists  $x \in V(s)$  such that  $\exists y \in V(s), (y, x) \in E(s)$  but  $\exists z \in V(t), (z, x) \in E(t)$ . We get  $(x, x) \in E(\hat{\sigma}_8[s])$  but  $(x, x) \notin E(\hat{\sigma}_8[t])$ . Hence  $\hat{\sigma}_8[s] \approx \hat{\sigma}_8[t] \notin IdSG$ .

Suppose that there exists  $x' \in V(s)$  such that  $\exists y' \in V(s), (x', y') \in E(s^d)$ but  $\exists z' \in V(t), (x', z') \in E(t^d)$ . We see that  $(x', x') \in E(\hat{\sigma}_7[s])$  but  $(x', x') \notin E(\hat{\sigma}_7[t])$ . Hence  $\hat{\sigma}_7[s] \approx \hat{\sigma}_7[t] \notin IdSG$ .

Suppose that there exists  $x' \in V(s)$  such that  $\exists y' \in V(s), (y', x') \in E(s^d)$ but  $\exists z' \in V(t), (z', x') \in E(t^d)$ . We get  $(x', x') \in E(\hat{\sigma}_9[s])$  but  $(x', x') \notin E(\hat{\sigma}_9[t])$ . Hence  $\hat{\sigma}_9[s] \approx \hat{\sigma}_9[t] \notin IdSG$ .

Conversely, assume that  $s \approx t$  is an identity in SG satisfying (i),(ii), (iii), (iv) and (v).

We have to prove that  $s \approx t$  is closed under all graph hypersubstitutions from  $M_{SG}$ .

If  $\sigma \in \{\sigma_0, \sigma_{10}\}$ , then  $\sigma$  is proper and we get that  $\hat{\sigma}[s] \approx \hat{\sigma}[t] \in IdSG$ . By assumption,  $\hat{\sigma}_5[s] = s^d \approx t^d = \hat{\sigma}_5[t]$  and  $\hat{\sigma}_1[s] = L(s) = L(t) = \hat{\sigma}_1[t]$ ,  $\hat{\sigma}_2[s] = L(s^d) = L(t^d) = \hat{\sigma}_2[t], \hat{\sigma}_3[s] = L(s)L(s) = L(t)L(t) = \hat{\sigma}_3[t], \hat{\sigma}_4[s] = L(s^d)L(s^d) = L(t^d)L(t^d) = \hat{\sigma}_4[t]$ .

Because of  $\sigma_{10} \circ_N \sigma_5 = \sigma_{11}$  and  $\hat{\sigma}_{10}[\hat{\sigma}_5[t']] = \hat{\sigma}_{10}[t'^d]$  for all  $t' \in W_\tau(X)$ . We have  $\hat{\sigma}_{11}[s] \approx \hat{\sigma}_{11}[t]$  is an identity in  $\mathcal{SG}$ .

Next, we will prove that  $\hat{\sigma}_6[s] \approx \hat{\sigma}_6[t] \in IdS\mathcal{G}$ ,  $\hat{\sigma}_7[s] \approx \hat{\sigma}_7[t] \in IdS\mathcal{G}$ ,  $\hat{\sigma}_8[s] \approx \hat{\sigma}_8[t] \in IdS\mathcal{G}$  and  $\hat{\sigma}_9[s] \approx \hat{\sigma}_9[t] \in IdS\mathcal{G}$ . We see that  $L(\hat{\sigma}_6[s]) = L(s) = L(t) = L(\hat{\sigma}_6[t])$ ,  $L(\hat{\sigma}_7[s]) = L(s^d) = L(t^d) = L(\hat{\sigma}_7[t])$ ,  $L(\hat{\sigma}_8[s]) = L(s) = L(t) = L(\hat{\sigma}_8[t])$ ,  $L(\hat{\sigma}_9[s]) = L(s^d) = L(t^d) = L(\hat{\sigma}_9[t])$ . Since  $\sigma_6, \sigma_7, \sigma_8$  and  $\sigma_9$  are regular, we have  $V(\hat{\sigma}_6[s]) = V(s) = V(t) = V(\hat{\sigma}_6[t])$ ,  $V(\hat{\sigma}_7[s]) = V(s) = V(t) = V(\hat{\sigma}_6[t])$ ,  $V(\hat{\sigma}_8[s]) = V(s) = V(t) = V(\hat{\sigma}_8[t])$ ,  $V(\hat{\sigma}_9[s]) = V(s) = V(t) = V(\hat{\sigma}_9[t])$ .

For any  $x, y \in V(s)$ , assume that  $(x, y) \in E(\hat{\sigma}_6[s])$  or  $(y, x) \in E(\hat{\sigma}_6[s])$ . Suppose that x = y (i.e.  $(x, x) \in E(\hat{\sigma}_6[s])$ . If  $(x, x) \in E(s)$ , then by Theorem 3.1(iii), we have  $(x, x) \in E(t)$ . Therefore  $(x, x) \in E(\hat{\sigma}_6[t])$ . If  $(x, x) \notin E(s)$ , then there exists z such that  $(x, z) \in E(s)$ . By (ii), there exists w such that  $(x, w) \in E(t)$ . Therefore  $(x, x) \in E(\hat{\sigma}_6[t])$ . If  $x \neq y$ , then  $(x, y) \in E(s)$  or  $(y, x) \in E(s)$ . By Theorem 3.1 (iii), we get  $(x, y) \in E(t)$  or  $(y, x) \in E(t)$ . Hence  $(x, y) \in E(\hat{\sigma}_6[t])$  or  $(y, x) \in E(\hat{\sigma}_6[t])$ . By the same way, we can prove that, if  $(x, y) \in E(\hat{\sigma}_6[t])$  or  $(y, x) \in E(\hat{\sigma}_6[t])$ , then  $(x, y) \in E(\hat{\sigma}_6[s])$  or  $(y, x) \in E(\hat{\sigma}_6[s])$ . Hence  $\hat{\sigma}_6[s] \approx \hat{\sigma}_6[t] \in IdS\mathcal{G}$ .

For any  $x, y \in V(s)$ , assume that  $(x, y) \in E(\hat{\sigma}_8[s])$  or  $(y, x) \in E(\hat{\sigma}_8[s])$ . Suppose that x = y (i.e.  $(x, x) \in E(\hat{\sigma}_8[s])$ . If  $(x, x) \in E(s)$ , then by Theorem 3.1(iii), we have  $(x, x) \in E(t)$ . Therefore  $(x, x) \in E(\hat{\sigma}_8[t])$ . If  $(x, x) \notin E(s)$ , then there exists z such that  $(z, x) \in E(s)$ . By (iii), there exists w such that  $(w, x) \in E(t)$ . Therefore  $(x, x) \in E(\hat{\sigma}_8[t])$ . If  $x \neq y$ , then  $(x, y) \in E(s)$  or  $(y, x) \in E(s)$ . By Theorem 3.1(iii), we get  $(x, y) \in E(t)$  or  $(y, x) \in E(s)$ . Hence  $(x, y) \in E(\hat{\sigma}_8[t])$  or  $(y, x) \in E(\hat{\sigma}_8[t])$ . By the same way, we can prove that, if  $(x, y) \in E(\hat{\sigma}_8[t])$  or  $(y, x) \in E(\hat{\sigma}_8[t])$ , then  $(x, y) \in E(\hat{\sigma}_8[s])$  or  $(y, x) \in E(\hat{\sigma}_8[s])$ . Hence  $\hat{\sigma}_8[s] \approx \hat{\sigma}_8[t] \in IdS\mathcal{G}$ .

For any  $x, y \in V(s)$ , assume that  $(x, y) \in E(\hat{\sigma}_7[s])$  or  $(y, x) \in E(\hat{\sigma}_7[s])$ . Suppose that x = y (i.e.  $(x, x) \in E(\hat{\sigma}_7[s])$ . If  $(x, x) \in E(s^d)$ , then by assumption (i) and Theorem 3.1(iii), we have  $(x, x) \in E(t^d)$ . Hence  $(x, x) \in E(\hat{\sigma}_7[t])$ . If  $(x, x) \notin E(s)$ , then there exists z such that  $(x, z) \in E(s^d)$ . By (iv), there exists w such that  $(x, w) \in E(t^d)$ . Therefore  $(x, x) \in E(\hat{\sigma}_7[t])$ . If  $x \neq y$ , then  $(x, y) \in E(s^d)$  or  $(y, x) \in E(s^d)$ . By assumption (i) and Theorem 3.1 (iii), we get  $(x, y) \in E(t^d)$  or  $(y, x) \in E(t^d)$ . Hence  $(x, y) \in E(\hat{\sigma}_7[t])$  or  $(y, x) \in E(\hat{\sigma}_7[t])$ . By the same way, we can prove that, if  $(x, y) \in E(\hat{\sigma}_7[t])$  or  $(y, x) \in E(\hat{\sigma}_7[t])$ , then  $(x, y) \in E(\hat{\sigma}_7[s])$  or  $(y, x) \in E(\hat{\sigma}_7[s])$ .

For any  $x, y \in V(s)$ , assume that  $(x, y) \in E(\hat{\sigma}_9[s])$  or  $(y, x) \in E(\hat{\sigma}_9[s])$ . Suppose that x = y (i.e.  $(x, x) \in E(\hat{\sigma}_9[s])$ . If  $(x, x) \in E(s^d)$ , then by assumption (i) and Theorem 3.1(iii), we have  $(x, x) \in E(t^d)$ . Hence  $(x, x) \in E(\hat{\sigma}_9[t])$ . If  $(x, x) \notin E(s)$ , then there exists z such that  $(z, x) \in E(s^d)$ . By (v), there exists w such that  $(w, x) \in E(t^d)$ . Therefore  $(x, x) \in E(s^d)$ . By (v), there  $(x, y) \in E(s^d)$  or  $(y, x) \in E(s^d)$ . By assumption (i) and Theorem 3.1 (iii), we get  $(x, y) \in E(t^d)$  or  $(y, x) \in E(t^d)$ . Hence  $(x, y) \in E(\hat{\sigma}_9[t])$  or  $(y, x) \in E(\hat{\sigma}_9[t])$ . By the same way, we can prove that, if  $(x, y) \in E(\hat{\sigma}_9[t])$  or  $(y, x) \in E(\hat{\sigma}_9[t])$ , then  $(x, y) \in E(\hat{\sigma}_9[s])$  or  $(y, x) \in E(\hat{\sigma}_9[s])$ .

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